

Singular kinetic equations

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- Nonlinear martingale problem
- Propagation of chaos
- Nonlinear kinetic Fokker-Planck equation

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Motivation

- Consider the following N -particles system:

$$\begin{cases} dX_t^{N,i} = V_t^{N,i} dt, \\ dV_t^{N,i} = b(Z_t^{N,i}) dt + \frac{1}{N} \sum_{j \neq i} K(X_t^{N,i} - X_t^{N,j}) dt + \sqrt{2} dB_t^i, \end{cases}$$

where $i = 1, 2, \dots, N$

- $Z^{N,i} = (X^{N,i}, V^{N,i}) \in \mathbb{R}^{2d}$: position and velocity of particle number i
- b : the force field depending on both position and velocity
- K : interaction kernel.
- B^i : independent Brownian motions (random phenomena)

DDSDE

- When b and K are smooth, the solution of the N -particles system $Z^{N,i}$ converges to the solution to the following Distribution Dependent SDE (DDSDE):

$$\begin{cases} dX_t = V_t dt \\ dV_t = b(Z_t) dt + \int_{\mathbb{R}^d} K(X_t - y) \mu_t(dy) dt + dB_t, \end{cases} \quad (1)$$

where μ_t is the distribution of X_t and B_t is a standard BM.

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where μ_t is the distribution of X_t and B_t is a standard BM.

- Well-known results

[Jabin and Wang \(JFA-16\)](#) Assume $K \in L^\infty$. Well-posedness for Fokker-Plank equation and propagation of chaos.

[Chaudru de Raynal \(AIHP-15\)](#) Assume $K \equiv 0$ and $b \in \mathbf{C}_x^\alpha \cap \mathbf{C}_v^\beta$ with $\alpha > \frac{2}{3}$, $\beta > 0$. Well-posedness for SDE equation (1).

[Zhang \(China Math-18\)](#) Assume $K \equiv 0$ and $(1 - \Delta_x)^{\frac{1}{3}} b \in L^p$ with $p > 2(2d + 1)$. Well-posedness for SDE equation (1).

[Wang and Zhang \(SIAM-16\)](#) Hölder Dini assumption

[Chaudru de Raynal, Honoré and Menozzi 18](#) Chain case

[Chen and Zhang \(JMPA-18\) & Hao, Wu and Zhang \(JMPA-20\)](#) Non-local case

[Jair 19 & Lacker 21](#) Propagation and chaos

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Motivation

- Recently, the study of the SDEs driven by singular drift b is more and more popular, especially the distribution case. Such singular diffusions appear as models for stochastic processes in random media, i.e. b would also be random, but independent of BM B .

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- For the following first order SDE:

$$dX_t = b(X_t)dt + dB_t,$$

- Brox (AoP-86): Brox diffusion (b is a space white noise)
- Delarue and Diel (PTRF-16): 1-d distribution drift b (Rough path)
- Cannizzaro and Chouk (AoP-18): Multidimensional case with distribution drift b (Paracontrolled calculus).

Motivation

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- (Question:)
Could we understand the kinetic DDSDE (1) with singular noise b ?

Our model

- Let b be a Gaussian noise in \mathbb{R}^{2d} with spectral measure μ , i.e. for any $f, g \in \mathcal{S}(\mathbb{R}^{2d})$,

$$\mathbb{E}[\langle b, f \rangle \langle b, g \rangle] = \int_{\mathbb{R}^{2d}} \hat{f}(\zeta) \hat{g}(-\zeta) \mu(d\zeta).$$

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$$\mathbb{E}[\langle b, f \rangle \langle b, g \rangle] = \int_{\mathbb{R}^{2d}} \hat{f}(\zeta) \hat{g}(-\zeta) \mu(d\zeta).$$

- For example, when $\mu(d\zeta) = d\zeta$ is the Lebesgue measure of \mathbb{R}^{2d} , b is a white noise in \mathbb{R}^{2d} ; when $\mu(d\zeta) = \delta(d\xi)d\eta$ with $\zeta = (\xi, \eta) \in \mathbb{R}^{2d}$, $b(x, v) = b(v)$ is the white noise in \mathbb{R}_v^d .
- When b is a white noise, $b \in \mathcal{C}^{-\frac{1}{2}-}$ is not a function, but only a distribution.

Our model

- Consider the following kinetic DDSDE with distribution drift b and interaction kernel K ,

$$\begin{cases} dX_t = V_t dt \\ dV_t = b(Z_t) dt + \int_{\mathbb{R}^d} K(X_t - y) \mu_t(dy) dt + dB_t. \end{cases} \quad (\star)$$

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- (Questions:)
 - Definition-Nonlinear martingale problem
-Paracontrolled calculus
 - Existence and Uniqueness-what's the condition of μ and K .
 - Propagation of chaos

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Kinetic operator

- To set up the martingale problem to DDSDE (\star), it is important to establish the well-posedness for the related PDE:

$$\partial_t u = \Delta_v u + v \cdot \nabla_x u + b \cdot \nabla u + f, \quad u(0) = \varphi, \quad (\text{SKE})$$

where $u = u(t, z) = u(t, x, v)$.

- The following operator is called kinetic operator

$$\mathcal{L} := \partial_t - \Delta_v - v \cdot \nabla_x.$$

Kinetic operator

- In 1934, Kolmogorov found the fundamental solution of \mathcal{L} is the density $p_t(x, v)$ of the process $(\sqrt{2} \int_0^t B_s ds, \sqrt{2} B_t)$ and

$$p_t(x, v) = \left(\frac{2\pi t^4}{3}\right)^{-\frac{d}{2}} \exp\left(-\frac{3|x|^2 + |3x - 2tv|^2}{4t^3}\right).$$

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- More precisely, for any $z = (x, v)$, denote by the semigroup

$$P_t f(z) := \Gamma_t p_t * \Gamma_t f(z) = \mathbb{E}f\left(x + tv + \sqrt{2} \int_0^t B_s ds, v + B_t\right),$$

where

$$\Gamma_t f(z) := f(\Gamma_t z) := f(x + tv, v).$$

Then,

$$u(t) := P_t \varphi + \int_0^t P_{t-s} f(s) ds$$

solves the following kinetic equation:

$$\mathcal{L}u = f, \quad u(0) = \varphi.$$

Scaling

- Notice that

$$p_t(x, v) = t^{-2d} p_1(t^{\frac{3}{2}} x, t^{\frac{1}{2}} v).$$

- The scaling of x and v is **3 : 1** in the kinetic equations. So, it is nature to consider the following metric:

$$|z_1 - z_2|_a := |x_1 - x_2|^{\frac{1}{3}} + |v_1 - v_2|, \quad z_i := (x_i, v_i), i = 1, 2.$$

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- For any $\alpha > 0$, define the anisotropic Hölder-Zygmund space C_a^α with the following norm

$$\|f\|_{C_a^\alpha} := \|f\|_\infty + \sup_{h \neq 0} \frac{\|\delta_h^{[\alpha]+1} f\|_\infty}{|h|_a},$$

where \square is the Gauss function and $\delta_h f(z) := f(z + h) - f(z)$.

Anisotropic Besov space

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- Let

$$B_j := \{\zeta \in \mathbb{R}^{2d}, 2^{j-1} < |\zeta|_a < 2^{j+1}/3\}$$

for $j \geq 0$ and $B_{-1} := \{|\zeta| < 2/3\}$.

- By a technical construction, there is a unity of partition $\{\phi_j^a\}_{j \geq -1} \subset \mathbf{C}_0^\infty$ belonging to $\cup_{j \geq -1} B_j$ and

$$\phi_j^a(\xi, \eta) = \phi_0^a(2^{-3j}\xi, 2^{-j}\eta).$$

Anisotropic Besov space

- For given $j \geq -1$, the block operator \mathcal{R}_j^a is defined on \mathcal{S}' by

$$\mathcal{R}_j^a f(z) := \mathcal{F}^{-1}(\phi_j^a \mathcal{F}(f))(z) = \mathcal{F}^{-1}(\phi_j^a) * f(z).$$

- For any $\alpha \in \mathbb{R}$, $p, q \in [1, \infty]$, define the **anisotropic Besov** space $\mathbf{B}_{p,q}^{a,\alpha}$ with the following norm:

$$\|f\|_{\mathbf{B}_{p,q}^{a,\alpha}} := \left(\sum_{i \geq -1} 2^{\alpha q i} \|\mathcal{R}_i^a f\|_q^q \right)^{\frac{1}{q}}.$$

- It is well-known that for $\alpha > 0$, $\mathbf{C}_a^\alpha = \mathbf{B}_{\infty,\infty}^{a,\alpha}$. For simplicity, we denote by

$$\mathbf{C}_a^\alpha := \mathbf{B}_{\infty,\infty}^{a,\alpha}$$

for all $\alpha \in \mathbb{R}$ in the sequel.

Weighted anisotropic Besov space

- The noise has a blow up when the position-velocity space \mathbb{R}^{2d} is not compact. We need a weight to balance the increasing (**blow up**) as $z \rightarrow \infty$ in \mathbb{R}^{2d}
- Let \mathcal{P}_W be the set of all function in the following form

$$\rho_\delta(z) = ((1 + |x|^2)^{1/3} + |v|^2)^{-\delta/2} \asymp (1 + |z|_a)^{-\delta}, \quad \delta \in \mathbb{R}.$$

- For any $\alpha \in \mathbb{R}$ and $\rho \in \mathcal{P}_W$, define the **weight anisotropic Besov space** $\mathbf{C}_a^\alpha(\rho)$ with the following norm:

$$\|f\|_{\mathbf{C}_a^\alpha(\rho)} := \|\rho f\|_{\mathbf{C}_a^\alpha}.$$

Kinetic Hölder space

- Recall

$$\Gamma_t f(z) := f(\Gamma_t z), \quad \Gamma_t z := (x + tv, v).$$

- Let $\alpha \in (0, 2)$, $\rho \in \mathcal{P}_W$ and $T > 0$. Define

$$\mathbb{S}_{T,a}^\alpha(\rho) := \left\{ f : \|f\|_{\mathbb{S}_{T,a}^\alpha(\rho)} := \|f\|_{L_T^\infty \mathbf{C}_a^\alpha(\rho)} + \|f\|_{\mathbf{C}_{T;\Gamma}^{\alpha/2} L^\infty(\rho)} < \infty \right\},$$

where for $\beta \in (0, 1)$,

$$\begin{aligned} \|f\|_{\mathbf{C}_{T;\Gamma}^\beta L^\infty(\rho)} &:= \sup_{0 \leq t \leq T} \|f(t)\|_{L^\infty(\rho)} \\ &+ \sup_{0 < |t-s| \leq 1} \frac{\|f(t) - \Gamma_{t-s} f(s)\|_{L^\infty(\rho)}}{|t-s|^\beta}. \end{aligned}$$

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- The reason why we introduce this kinetic Hölder space is because

$$\|P_t f - \Gamma_t f\|_\infty \leq C_\delta t^{\frac{\delta}{2}} \|f\|_{\mathbf{C}_a^\delta} \quad \delta \in (0, 2).$$

Schauder's estimate

- Denote by

$$\mathcal{I} := \int_0^t P_{t-s} \, ds.$$

Theorem 1 (Schauder's estimate)

Let $\beta \in (0, 2)$ and $\rho \in \mathcal{P}_W$. For any $T > 0$, there is a constant $C = C(d, \beta, \rho, T) > 0$ such that for all $f \in L_T^\infty \mathbf{C}_a^{-\beta}(\rho)$,

$$\|\mathcal{I}f\|_{\mathbb{S}_{T,a}^{2-\beta}(\rho)} \leq C \|f\|_{L_T^\infty \mathbf{C}_a^{-\beta}(\rho)}.$$

Linear singular kinetic equation

- Consider the following kinetic equation

$$\partial_t u = \Delta_v u + v \cdot \nabla_x u + b \cdot \nabla_v u + f, \quad u(0) = \varphi.$$

- We are interested in the following noise b

$$b \in \mathbf{C}_a^{-\alpha}(\rho_\kappa), \quad \alpha \in \left(\frac{1}{2}, \frac{2}{3}\right) \text{ and } \kappa \in (0, 1).$$

- By Schauder's estimate, the best regularity of the solution u is in

$$L^\infty([0, T]; \mathbf{C}_a^{2-\alpha}(\rho_\kappa)).$$

Difficulties

1 (ill-defined problem) $b \cdot \nabla_v u$ does not make sense since

$$\mathbf{C}_a^{-\alpha} \times \mathbf{C}_a^{1-\alpha} \ni (b, \nabla_v u) \rightarrow b \cdot \nabla_v u \in \mathbf{C}_a^{\alpha \wedge (1-\alpha)} \text{ only if } 1 - 2\alpha > 0.$$

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2 (weight lose problem) The weight ρ_κ here always make technical difficult, roughly speaking,

$$u \in \mathbf{C}_a^{\dots}(\rho_\kappa) + b \in \mathbf{C}_a^{\dots}(\rho_\kappa) \Rightarrow b \cdot \nabla_v u \in \mathbf{C}_a^{\dots}(\rho_{2\kappa}).$$

By Schauder's estimate again,

$$u \in \mathbf{C}_a^{\dots}(\rho_{2\kappa}) \Rightarrow b \cdot \nabla_v u \in \mathbf{C}_a^{\dots}(\rho_{3\kappa}) \Rightarrow u \in \mathbf{C}_a^{\dots}(\rho_{3\kappa}),$$

$$\Rightarrow u \in \mathbf{C}_a^{\dots}(\rho_{\infty\kappa}) \quad \text{blow up!}$$

Methods to solve the difficulties

I (Paracontrolled calculus) Transfer the ill-defined problem from

$$b \cdot \nabla_v u \quad \text{to} \quad b \cdot \nabla_v \mathcal{I}b.$$

from $\int_0^t f(w_s)dw_s$ to $\int_0^t w_s dw_s$ similar in rough path.

More precisely, let $u = u(b, b \cdot \nabla_v \mathcal{I}b)$.

- This method was first proposed by Gubinelli, Imkeller and Perkowski in 2015 for $\partial_t - \Delta$.
- However, our model is $\partial_t - \Delta_v - v \cdot \nabla_x$. This kinetic operator is not a multiplication operator like $\partial_t - \Delta$.
- It is interesting and not easy to establish the paracontrolled calculus for the kinetic equations.

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- 2 (Localization)

- This method is in Zhang, Zhu and Zhu's paper: arXiv:2007.06783 for $\partial_t - \Delta$.
- Key points:

$$\|f\|_{\mathbf{C}^\beta(\rho)} \asymp \sup_z \rho(z) \|f\chi_z\|_{\mathbf{C}^\beta}$$

and

$$|\nabla_v \rho(z)| \lesssim \rho_1(z) \rho(z).$$

Renormalization of Gauss noise b

- Recall that

$$\mathbb{E}[\langle b, f \rangle \langle b, g \rangle] = \int_{\mathbb{R}^{2d}} \hat{f}(\zeta) \hat{g}(-\zeta) \mu(d\zeta).$$

- Suppose that for $\zeta = (\xi, \eta) \in \mathbb{R}^{2d}$

$$\mu(d\xi, d\eta) = \mu(-d\xi, d\eta) = \mu(d\xi, -d\eta).$$

- (H $^\beta$)** For some $\beta \in (\frac{1}{2}, \frac{2}{3})$,

$$\sup_{\zeta' \in \mathbb{R}^{2d}} \int_{\mathbb{R}^{2d}} \frac{\mu(d\zeta)}{(1 + |\zeta + \zeta'|_a)^{2\beta}} < \infty.$$

Main result for linear kinetic equations

Theorem 2

Let $\alpha \in (\frac{1}{2}, \frac{2}{3})$, $\vartheta := \frac{9}{2-3\alpha}$, $\kappa_f \in \mathbb{R}$,

$$\delta := (2\vartheta + 2)\kappa \leq 1 \quad \text{and} \quad \bar{\kappa} := (2\vartheta + 1)\kappa + \kappa_f.$$

Assume that (\mathbf{H}^β) holds for some $\beta < \alpha$. For any $T > 0$, $\kappa > 0$,

$$f \in L_T^\infty \mathbf{C}_a^{\alpha-1+}(\rho_{\kappa_f}) \quad \text{or} \quad f = b, \quad \text{and} \quad \varphi \in \mathbf{C}_a^{\alpha+1+}(\rho_{\kappa_f-\kappa}),$$

there is a unique paracontrolled solution $u \in \mathbb{S}_{T,a}^{2-\alpha}(\rho_{\bar{\kappa}})$ to PDE (SKE).

Examples

- 1 For any $\lambda \in (d - \frac{1}{3}\alpha, d)$,

$$\mu(d\zeta) = \frac{d\xi}{|\xi|^\lambda} \delta(d\eta), \quad \zeta = (\xi, \zeta),$$

where $d\xi$ is the Lebesgue measure on \mathbb{R}^d and $\delta(d\eta)$ is the Dirac measure.

When $d = 1$,

$$b(x, \nu) = b(x) = \partial_x B_H(x)$$

is the derivative of a fractional BM with Hurst parameter $H = \frac{1+\lambda}{2}$.

Examples

1 For any $\lambda \in (d - \frac{1}{3}\alpha, d)$, $\mu(d\zeta) = \frac{d\xi}{|\xi|^\lambda} \delta(d\eta)$.

2 For any $\lambda \in (d - 2\alpha, d)$ and $\lambda \geq 0$,

$$\mu(d\zeta) = \delta(d\xi) \frac{d\eta}{|\eta|^\lambda}, \quad \zeta = (\xi, \eta).$$

When $d = 1$, $\lambda = 0$ is admissible, this time $b(x, v) = \xi(v)$ is a space white noise on \mathbb{R}_v .

Examples

- 1 For any $\lambda \in (d - \frac{1}{3}\alpha, d)$, $\mu(d\zeta) = \frac{d\xi}{|\xi|^\lambda} \delta(d\eta)$.
- 2 For any $\lambda \in (d - 2\alpha, d)$ and $\lambda \geq 0$, $\mu(d\zeta) = \delta(d\xi) \frac{d\eta}{|\eta|^\lambda}$.
- 3 For any $\lambda_1, \lambda_2 \in [0, d)$ with $3\lambda_1 + \lambda_2 > 4d - 2\alpha$,

$$\mu(d\zeta) = \frac{d\xi d\eta}{|\xi|_1^\lambda |\eta|_2^\lambda}, \quad \zeta = (\xi, \eta).$$

Notice that, when $d = 1$, $\lambda_2 = 0$ is admissible.

In this case, b can be regarded as the white noise in v -part.

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Singular kinetic DDSDE

- Now, let's go back to the original problem:

$$\begin{cases} dX_t = V_t dt \\ dV_t = b(Z_t) dt + \int_{\mathbb{R}^d} K(X_t - y) \mu_t(dy) dt + dB_t, \end{cases} \quad (\star)$$

where $b \in \mathbf{C}_a^{-\alpha}(\rho_\kappa)$ for some $\alpha \in (\frac{1}{2}, \frac{2}{3})$, $\kappa > 0$ and satisfying the condition (\mathbf{H}^β) with some $\beta < \alpha$.

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where $b \in \mathbf{C}_a^{-\alpha}(\rho_\kappa)$ for some $\alpha \in (\frac{1}{2}, \frac{2}{3})$, $\kappa > 0$ and satisfying the condition (\mathbf{H}^β) with some $\beta < \alpha$.

- Let $\mathcal{P}(E)$ be the set of all probability measures over some Banach space E . Denote by $\mathcal{P}_\delta(\mathbb{R}^{2d})$ be the space of all $\nu \in \mathcal{P}(\mathbb{R}^{2d})$ with

$$\int_{\mathbb{R}^{2d}} \rho_{-\delta}(z) \nu(dz) \asymp \int_{\mathbb{R}^{2d}} (1 + |z|_a)^\delta \nu(dz) < \infty, \quad \delta \geq 0.$$

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- For any $T > 0$, denote by $\mathcal{C}_T := C([0, T]; \mathbb{R}^{2d})$ and let \mathcal{B}_t be the natural σ -filtration, and z be the canonical process over \mathcal{C}_T , i.e.

$$z_t(\omega) = (x_t(\omega), v_t(\omega)) = \omega_t, \quad \omega \in \mathcal{C}_T.$$

Nonlinear martingale problem

- For any continuous curve $\mu : [0, T] \rightarrow \mathcal{P}(\mathbb{R}^d)$ with respect to the weak convergence, define

$$\mathcal{L}_t^\mu := \Delta_v + v \cdot \nabla_x + (b + K * \mu_t) \cdot \nabla_v.$$

- Let $f \in L_T^\infty \mathbf{C}_b(\mathbb{R}^{2d})$, $\varphi \in \mathbf{C}_a^{\alpha+1+}(\mathbb{R}^{2d})$ and $\vartheta = \frac{9}{2-3\alpha}$. We call $(u, f, \varphi) \in A_T^\mu$ if $u \in \mathbb{S}_{T;a}^{2-\alpha}(\rho_{2(\vartheta+1)\kappa})$ is the paracontrolled solution to the following linear kinetic equation:

$$\partial_t u + \mathcal{L}_t^\mu u = f, \quad u(T) = \varphi.$$

Nonlinear martingale problem

Definition 3 (Nonlinear martingale problem)

Let $\delta > 0$. A probability measure $\mathbb{P} \in \mathcal{P}(\mathcal{C}_T)$ is called a nonlinear martingale solution to DDSDE (\star) starting from $\nu \in \mathcal{P}_\delta(\mathbb{R}^{2d})$, if $\mathbb{P} \circ z_0^{-1} = \nu$ and for all $(u, f, \varphi) \in A_T^\mu$,

$$M_t := u(t, z_t) - u(0, z_0) - \int_0^t f(s, z_s) ds$$

is a \mathbb{P} -martingale respect to $(\mathcal{B}_t)_{t \in [0, T]}$, where $\mu_t = \mathbb{P} \circ x_t^{-1}$.

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Theorem 4 (Main result)

Assume that (\mathbf{H}^β) and $K \in \mathbf{C}^{\frac{\alpha-1+}{3}}$. For any $\delta > 0$, there exists at least one nonlinear martingale solution to DDSDE (\star) . Moreover, if K is bounded measurable, then there exists at most one solution.

N -particle system with singular drift

- Recall the following N -particles system:

$$\begin{cases} dX_t^{N,i} = V_t^{N,i} dt, \\ dV_t^{N,i} = b(Z_t^{N,i}) dt + \frac{1}{N} \sum_{j \neq i} K(X_t^{N,i} - X_t^{N,j}) dt + \sqrt{2} dB_t^i. \end{cases} \quad (\mathcal{N})$$

- Denote by $B(\mathbf{z}) := B(z_1, \dots, z_N) := (b(z_1), \dots, b(z_N))$. Then,

$$B(\mathbf{z}) \cdot \nabla_{\mathbf{v}} \mathcal{I}_N B(\mathbf{z}) = (b \cdot \nabla_{v_1} \mathcal{I} b(z_1), \dots, b \cdot \nabla_{v_1} \mathcal{I} b(z_N))$$

is well-defined, where $\mathcal{I}_N := \mathcal{I}^{\otimes N}$.

- Hence, by the same argument above, we have the well-posedness for the linear martingale problem to N -particle system (\mathcal{N}) .

Propagation of chaos

- Denote by $\mu^N \in \mathcal{P}(\mathcal{C}_T)$ and $\mu \in \mathcal{P}(\mathcal{C}_T)$ be the distribution of $Z^{N,i}$ and the distribution to the solution of non-linear martingale problem respectively.
- Let b_n be the modifier of b .
- Denote by $\mu_n^N \in \mathcal{P}(\mathcal{C}_T)$ and $\mu_n \in \mathcal{P}(\mathcal{C}_T)$ be the distribution of the i -th particle in the N -particle system (\mathcal{N}) with $b = b_n$ and the distribution to the solution of DDSDE with $b = b_n$ respectively.

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- (Lacker 2021)

$$\|\mu_n^N - \mu_n\|_{TV} \leq 4\sqrt{T}(1 + \|K\|_\infty^2)e^{3T\|K\|_\infty^2} \frac{1}{N}.$$

- Notice that the constant

$$C := 4\sqrt{T}(1 + \|K\|_\infty^2)e^{3T\|K\|_\infty^2}$$

is independence of n !

Propagation of chaos

- By the argument in DDSDE, we have for any $N \in \mathbb{N}$,

$$\mu_n^N \rightarrow \mu^N, \quad \mu_n \rightarrow \mu \text{ weakly as } n \rightarrow \infty.$$



$$\begin{array}{ccc} \mu^N & \xleftarrow{w} & \mu_n^N \\ \downarrow w & & \downarrow TV \\ \mu & \xleftarrow{w} & \mu_n \end{array}$$

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- For precisely, for any $f \in C_b(\mathcal{C}_T)$,

$$\begin{aligned} |\mu(f) - \mu^N(f)| &\leq \lim_{n \rightarrow \infty} |\mu(f) - \mu_n(f)| \\ &\quad + \sup_n |\mu_n(f) - \mu_n^N(f)| \\ &\quad + \lim_{n \rightarrow \infty} |\mu^N(f) - \mu_n^N(f)| \\ &\leq \frac{C}{N} \|f\|_\infty. \end{aligned}$$

Nonlinear Fokker-Planck equation

- Finally, we'd like to study the density of the martingale solution to DDSDE.
- (Question:)
 - 1 Whether the solution admit a density?
 - 2 Whether the density satisfy the following Fokker-Planck equation:

$$\partial_t u = \Delta_v u - v \cdot \nabla u - \operatorname{div}_v \left((b + K * \langle u \rangle) u \right), \quad u(0) = u_0,$$

where $\langle u \rangle(t, x) := \int_{\mathbb{R}^d} u(t, x, v) dv$ and $\nu(dz) = u_0(z) dz$?

Assumption: b is the Gauss noise satisfying (\mathbf{H}^β) with $\beta < \alpha$ and

$$\operatorname{div}_v b \equiv 0 \quad \text{and} \quad u_0 \in L^1 \cap \mathbf{C}_a^{\alpha+1+}.$$

- Consider the following singular kinetic Fokker-Planck equation

$$\partial_t u + v \cdot \nabla_x = \Delta_v u + b \cdot \nabla_v u + K * \langle u \rangle \cdot \nabla_v u, \quad u(0) = u_0.$$

Here $\langle u \rangle(t, x) := \int_{\mathbb{R}^d} u(t, x, v) dv$.

Conditions

(H₁) $K \in \cup_{\beta > \alpha - 1} \mathbf{C}^{\beta/3}$.

(H₂) K is bounded, for some $k > 0$,

$$\|\rho_{-k} u_0\|_{L^1} \asymp \int_{\mathbb{R}^{2d}} (1 + |z|_a)^k u_0(z) dz < \infty \quad (\text{energy condition}).$$

and

$$H(u_0) := \int_{\mathbb{R}^{2d}} u_0 \ln u_0 dz < \infty \quad (\text{entropy condition}).$$

(H₃)

$$\int_{\mathbb{R}^{2d}} u_0(z) dz = 1 \quad (\text{mass condition}).$$

Main result

Theorem 5

Let $\alpha \in (\frac{1}{2}, \frac{2}{3})$ and (\mathbf{H}^β) hold for some $\beta < \alpha$.

1 Under the condition (\mathbf{H}_1) , there is at least a solution $u \in L_T^\infty(\mathbf{C}_a^{2-\alpha}(\rho))$ to nonlinear Fokker-Planck equation with some weight $\rho \in \mathcal{P}_W$.

2 Under the condition (\mathbf{H}_2) , the solution is unique with

$$\|\rho_{-k}u(t)\|_{L^1} \leq C\|\rho_{-k}u_0\|_{L^1} \text{ (energy estimate);}$$

$$H(u(t)) \leq H(u_0) \text{ (entropy estimate).}$$

3 Under the condition (\mathbf{H}_1) , (\mathbf{H}_2) and (\mathbf{H}_3) , there is a unique solution u with $u \geq 0$ and

$$\int_{\mathbb{R}^{2d}} u(t, z) dz = 1 \text{ (mass conservation).}$$

Moreover, u is the density to the solution of the nonlinear martingale problem with initial data $\nu(dz) = u_0(z)dz$.

Thank you!

谢谢!